[This question paper contains 3 printed pages.]

3104

Your Roll No.

MEE

I.

Paper - EE.558

DIGITAL SIGNAL PROCESSING

Time: 3 hours

Maximum Marks: 100

(Write your Roll No. on the top immediately on receipt of this question paper.)

Attempt any five questions.

All questions carry equal marks.

- Design a FIR digital filter that will reject a very strong (60-Hz). Sinusoid, interference Contaminating a 200 Hz, useful Sinusoidal signal. Determine the gain of the filter so that the useful signal does not change amplitude. The filter works at a Sampling frequency (F_S = 500 Samples/sec). Compute output of the filter if the input is a 60 Hz. Sinusoid or a 200 Hz sinusoid with unit amplitude. (20)
- 2. (a) Write, if the following FIR systems are minimum, maximum or mixed phase.

(i)
$$h(n) = \{10, 9, -7, -8, 0, 5, 3\}$$

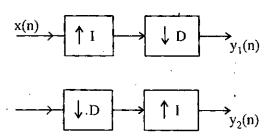
(ii)
$$h(n) = \{5, 4, -3, -4, 0, 2, 1\}$$
 (10)

(b) Write, why the Comb filter

$$H(Z) = \frac{1}{1 - aZ^{-D}}$$

can be used as a reverberator? (10)

- 3. Determine the impulse response of a FIR Lattice filter with parameters $K_1 = 0.6$, $K_2 = 0.3$, $K_3 = 0.5$, $K_4 = 0.9$. (20)
- 4. consider the two different ways of cascading a decimator with an interpolator shown below:



- (a) If D = I, show that the outputs of the two configurations are different. Hence, in general the two systems are not identical. (12)
- (b) Show that the two systems are identical if and only if D and I are relatively prime. (8)

5. In an Auto-regressive process, x(n) is characterized by the auto-correlation

Sequence
$$\gamma_{xx}(0) = 1$$
, $\gamma_{xx}(1) = \frac{1}{2}$, $\gamma_{xx}(2) = \frac{1}{8}$ and $\gamma_{xx}(3) = \frac{1}{64}$.

Use the Schür algorithm to determine the three reflection co-efficients K_1 , K_2 and K_3 . (20)

- 6. (a) Design the FIR Wiener filter using Levinson-Durbin algorithm. (10)
 - (b) Write the major design differences between the Wiener filter & Deconvolution filters. (10)
- 7. Write short note on the following:
 - (i) ESPRIT
 - (ii) Applications of Adaptive filters
 - (iii) LPC
 - (iv) Kalman filters (5×4=20)