

This question paper contains 3 printed pages.]

Your Roll No.

8467

A

B.Tech. (M)/IV

Paper EME-404 : ELECTIVE-I—CAD/CAM

Time : 3 Hours

Maximum Marks : 70

*(Write your Roll No. on the top immediately
on receipt of this question paper.)*

*Answer **five** questions, selecting at least **two**
from Part A and **two** from Part B.*

Assume missing data if any

PART-A

1. (a) Differentiate between :

(i) Absolute and incremental programming CNC machine

(ii) CNC and DNC 8

(b) Explain with examples the functioning of following used CNC :

(i) Input devices

(ii) Memory devices

(iii) Storage devices 6

[P.T.O.]

2. (a) Explain the following with respect to geometric modelling :
- (i) Sweep *or* Extrusion
 - (ii) Solid modelling 6
- (b) With example explain :
- (i) Bezier Curves
 - (ii) B-Splines 8
3. (a) While using AUTOCAD for draftings explain the following functions :
- (i) Co-ordinate System
 - (ii) Limits
 - (iii) Layers
 - (iv) Dimensioning 8
- (b) Write a note on 'Snap' and 'Ortho' in computer drafting system. 6
4. (a) Explain 'G' and 'M' codes used in NC part programming with four examples in each of them. 6
- (b) With examples explain *two* functions in each case used in drawing
- (i) Circle, (ii) Line, (iii) Point using APT language. 8

PART-B

5. (a) Define Robot. 2
- (b) Explain with neat sketch any *two* configuration of robots used in industry. 8

- (c) With neat sketch explain any ~~two~~ types of end effectors used as :
- (i) gripper (ii) tool in robots 4
6. (a) Define Group Technology 2
- (b) Explain the following coding system structures used in group technology
- (i) Hierarchical structure
- (ii) Chain-type structure
- (iii) Hybrid structure 6
- (c) Sketch and explain
- (i) Opitz Coding System
- (ii) Layout of machinery with functional grouping as per product requirements 6
7. (a) Explain with block diagram.
- (i) In-line FMS layout
- (ii) FMS loop layout 8
- (b) Explain various 'FMS Equipments' used in Flexible Manufacturing System. 6
8. Write short notes on :
- (i) Buffer Storage
- (ii) Parabolic interpolation
- (iii) Unidirectional approach CNC System
- (iv) Adoptive Control in CNC System 14